

23 OCT 2017

CH #13

* Electromagnetism *

charges

That branch of physics in which we study magnetism due to current.

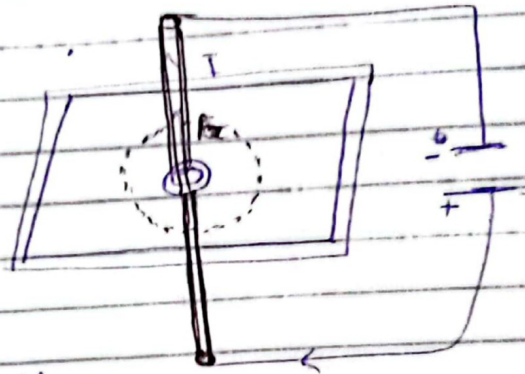
↳ ~~Orested~~ Orested discovered magnetic field.

MCQ:- Electricity and magnetism are both due to current (charges).

Compass needle:



* He said that magnetic field



is circular in shape

* When we reverse the direction of current the magnetic field also reverse.

* Magnetic field is represented by $B \rightarrow$ Magnetic Induction.

1. B depend on I .

2. Magnetic field is circular in shape.

3. If we reverse the direction of I , B also reverse.

* The direction of magnetic field can be determined by Right hand rule presented by Maxwell → A very good Mathematician.

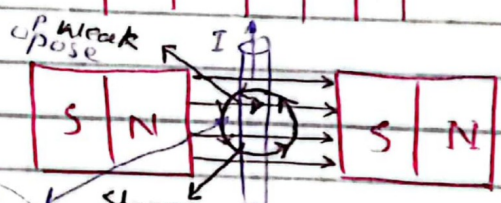
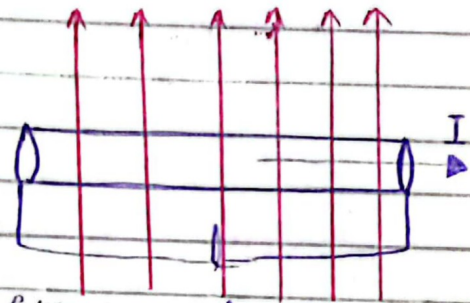
Exam Ques

Magnetic force on a current carrying conductor:-

$F_m \propto I$ — (i)

$F_m \propto L$ — (ii)

Length enclosed in Magnetic field



No net force

$F_m \propto B$ (iii) (Permanent Magnetic field)

$F_m \propto \sin \theta$ (iv) (B/w L and B).

Combining these relations:

$F_m \propto ILB \sin \theta$

$F_m = kILB \sin \theta$

$F_m = ILB \sin \theta$ — (v)

Magnitude of force acting on conductor:-



$$\vec{F}_m = I L B \sin \theta \hat{n}$$

$$\vec{F}_m = I (L B \sin \theta \hat{n}) \quad \text{--- (vi)}$$

$$\therefore \vec{A} \times \vec{B} = AB \sin \theta$$

$$L B \sin \theta \hat{n} = \vec{L} \times \vec{B} \quad \text{--- (vii)}$$

$$\boxed{\vec{F}_m = I (\vec{L} \times \vec{B})}$$

* Length is scalar quantity.

* The above \vec{L} is length vector.

Length vector:-
The direction of length vector

is along the direction of current and magnitude is equal to the magnitude of current.

Unit of B:-

Tesla $\rightarrow T$ is the unit of \vec{B} .

$$F_m = I L B \sin \theta$$

$$B = \frac{F_m}{I L \sin \theta}$$

$$1T = \frac{1N}{(1A)(1m) \sin 90^\circ}$$

$$\boxed{1T = \frac{1N}{1Am}}$$

MCCO:- Gauss is the unit of B in CGS System.

$$1 \text{ T} = 10^4 \text{ G}$$

$$1 \text{ G} = 10^{-4} \text{ T}$$

24 Oct, 2017

Magnetic flux and Flux Density:-

The no. of magnetic lines of force passes through an area placed in the magnetic field is called Magnetic flux.

$$\Phi_m = \vec{B} \cdot \vec{A}$$

$$\Phi_m = BA \cos(\theta) \quad \text{--- (1)}$$

① When $\theta = 0^\circ$

$$\Phi_m = BA \cos(0^\circ)$$

$$\Phi_m = BA \quad (\cos(0^\circ) = 1)$$

② When $\theta = 90^\circ$

$$\Phi_m = BA \cos(90^\circ)$$

$$\Phi_m = BA \cos(0)$$

Unit:-

$$\Phi_m = BA$$

$$1 \text{ Wb} = 1 \text{ T} \cdot 1 \text{ m}^2$$

Flux Density:-

$$\text{As, } \Phi_m = BA$$

$$B = \frac{\Phi_m}{A}$$

Flux Density:

"Flux per unit area is called Flux Density". $B = \frac{\Phi_m}{A}$

Exam Ques

Ampere's Circuital Law:-

This Law States that

"The magnitude of magnetic

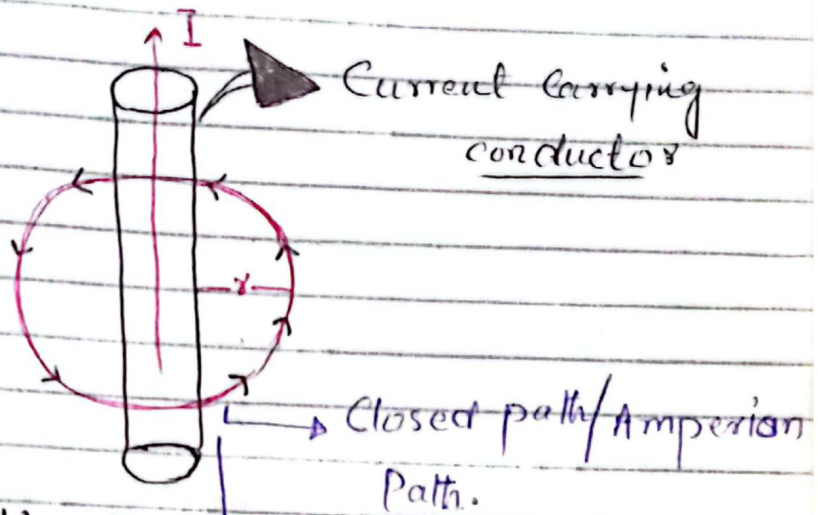
Induction (B) around a

Circuit Current Carrying

Conductor is directly proportional

to the magnitude of Current (I) passing through the

Conductor and Inversely proportional to distance (r) from the conductor.



Mathematically :- Behave like close circuit

$$B \propto I \quad \text{--- (i)}$$

$$B \propto \frac{1}{r} \quad \text{--- (ii)}$$

$$B \propto \frac{I}{r}$$

$$B = \frac{KI}{r} \quad \text{--- (iii)}$$

where, K is constant:

$$K = \frac{\mu_0}{2\pi}$$

μ_0 = permeability of Free Space

$$\mu_0 = 4\pi \times 10^{-7} \frac{Wb}{A \cdot m}$$

$$B = \frac{\mu_0 I}{2\pi r} \quad \text{--- (iv)}$$

permeability: μ :

"The ability of a material medium to permit by itself the magnetic field lines through itself is called permeability..."

* permeability of free space is

$$4\pi \times 10^{-7} \frac{\text{N/A}^2}$$

$$\vec{B} \cdot \vec{\Delta L} = B \Delta L \cos(\theta) \quad \text{--- (v)}$$

$$\vec{B} \cdot \vec{\Delta L} = B \Delta L \cos(0^\circ)$$

$$\cos(0^\circ) = 1$$

$$\vec{B} \cdot \vec{\Delta L} = B \Delta L$$

$$\sum \vec{B} \cdot \vec{\Delta L} = \sum B \Delta L$$

$$\sum \vec{B} \cdot \vec{\Delta L} = B \sum \Delta L$$

(B constant through all circles)

As $\sum \Delta L = \text{Circumference of circle} = 2\pi r$

$$\sum \Delta L = 2\pi r \quad \text{--- (vi)}$$

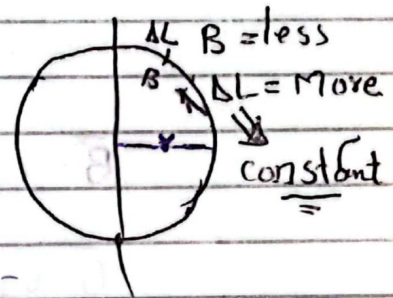
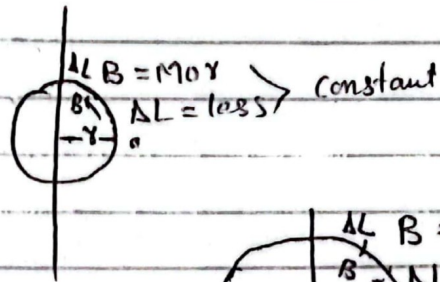
put eq (vi) and (v) in (5):

$$\sum \vec{B} \cdot \vec{\Delta L} = \frac{\mu_0 I}{2\pi r} (2\pi r)$$

$$\boxed{\sum \vec{B} \cdot \vec{\Delta L} = \mu_0 I}$$

The sum of Dot product of B and ΔL around a current carrying conductor is equal to $(\mu_0 \text{ not } \mu_0)$ times of the total current enclosed.

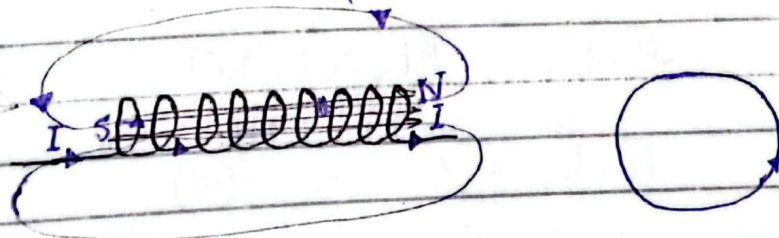
$$\oint B \cdot \Delta L = \mu_0 I$$



25 OCT, 2017

Apps of Ampere's Law:-
 Magnetic field due to Current in a Solenoid:

"When a wire is so systematically wound that it acquires a cylindrical shape is called Solenoid."



Magnetic field inside Solenoid:



→ magnetic field inside to solenoid

Now, Applying Ampere's Circuital law:

$$\sum \vec{B} \cdot \vec{\Delta L} = \mu_0 I$$

$$\sum_{i=1}^4 \vec{B} \cdot \vec{l}_i = \mu_0 I \quad \text{--- (i)}$$

$$\sum \vec{B} \cdot \vec{l}_i = \vec{B} \cdot \vec{l}_1 + \vec{B} \cdot \vec{l}_2 + \vec{B} \cdot \vec{l}_3 + \vec{B} \cdot \vec{l}_4 \quad \text{--- (ii)}$$

$$\vec{B} \cdot \vec{l}_1 = BL_1 \cos(0^\circ)$$

$$\vec{B} \cdot \vec{l}_1 = BL_1 \quad \text{--- (iii)}$$

$$\vec{B} \cdot \vec{l}_2 = BL_2 \cos(0)$$

$$\vec{B} \cdot \vec{l}_2 = BL_2 \cos(90^\circ)$$

$$\vec{B} \cdot \vec{l}_2 = 0 \quad \text{--- (iv)}$$

$$\vec{B} \cdot \vec{l}_3 = 0 \quad \text{--- (v)}$$

$\therefore \vec{B} = 0$ outside the Solenoid.....

$$\vec{B} \cdot \vec{l}_4 = BL_4 \cos(90^\circ)$$

$$\vec{B} \cdot \vec{l}_4 = 0 \quad \text{--- (vi)}$$

put eq (iii), (iv), (v), and (vi) in eq (ii):

$$\sum_{i=1}^4 \vec{B} \cdot \vec{l}_i = BL_1 + 0 + 0 + 0$$

$$\sum_{i=1}^4 \vec{B} \cdot \vec{l}_i = BL_1 \quad \text{--- (vii)}$$

put eq (vii) in (i):

$$BL_1 = \mu_0 I$$

$$L_1 = L$$

$$BL = \mu_0 I \rightarrow \text{Current passing through one loop of Solenoid.}$$

$$BL = \mu_0 N I \quad (\text{Current passes through "N" number of turns.})$$

$$B = \mu_0 \left(\frac{N}{L} \right) I$$

$$\frac{N}{L} = n$$

No. of loops per unit length = n

$$B = \mu_0 n I$$

μ_0 = permeability of free space

$$n = \frac{N}{L}$$

I = Total current.

It shows that Ampere's Law is applicable to any shape closed path.

Nm #2.

Data:

$$N = 1000 \text{ turns}$$

$$L = 0.5 \text{ m}$$

$$B = 2.5 \times 10^{-3} \text{ T}$$

Req: $I = ?$ $\mu_0 = 4\pi \times 10^{-7} \frac{\text{Wb}}{\text{A}\cdot\text{m}}$

$$B = \mu_0 n I$$

$$\therefore n = \frac{N}{L}$$

$$\boxed{I = \frac{BL}{\mu_0 N}}$$
 D.Y.S

Nm #1: Data:

$$I = 10 \text{ A}$$

$$B = 5 \times 10^{-5} \text{ T}$$

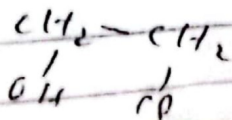
Req: $\mu_0 = 4\pi \times 10^{-7} \frac{\text{Wb}}{\text{A}\cdot\text{m}}$

$$r = ?$$

Applying Ampere's Law:

$$B = \frac{\mu_0 I}{2\pi r}$$

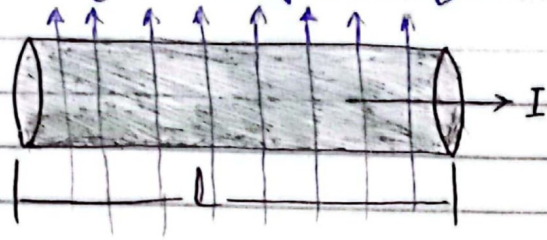
$$\boxed{r = \frac{\mu_0 I}{2\pi B}}$$
 D.Y.S



Force
26 Oct, 2017

Motion of a charge particle in a UMF (uniform magnetic field):

Exam Ques



$$F_m = I(\vec{l} \times \vec{B})$$

$$\vec{F}_m = ILB \sin\theta \hat{n}$$

$$F_m = ILB \sin\theta$$

When $\theta = 90^\circ$ $F_m = (F_m)_{\max}$

$$(F_m)_{\max} = ILB \sin(90^\circ)$$

$$(F_m)_{\max} = ILB \quad \text{--- (1)}$$

Magnetic force on all the charge particle... We calculate force on a single charge. So.

Then we replace $I = \frac{Q}{t}$ and then divide by 'No. of' charge.

$$I = \frac{Q}{t} \quad \text{--- (2)}$$

Total charge $\leftarrow Q = Nq$ --- (3)

$$n = \frac{N}{l}$$

$$N = nl \quad \text{--- (4)}$$

$$Q = n l q \quad \text{--- (5)}$$

put eq (5) in (2):

$$I = \frac{n l q}{t}$$

$$I = n \left(\frac{l}{t} \right) q$$

$$\text{As } \frac{l}{t} = v$$

$$\text{So, } I = n v q \quad \text{--- (6)}$$

put eq (6) in (1):

$$(F_m)_{\max} = n v q l B \quad \text{--- (7)}$$

Magnetic force on all the charges.

(ii) Magnetic force on single charge:

$$F_m = \frac{(F_m)_{\max}}{N} \quad \text{--- (8)}$$

(Total force)
total no. of charge

$$F_m = \frac{n v q l B}{n l}$$

$$F_m = q v B \quad \text{--- (9)}$$

Generalizing the equation:

$$F_m = q v B \sin \theta$$

$$\vec{F}_m = q (v B \sin \theta) \hat{n}$$

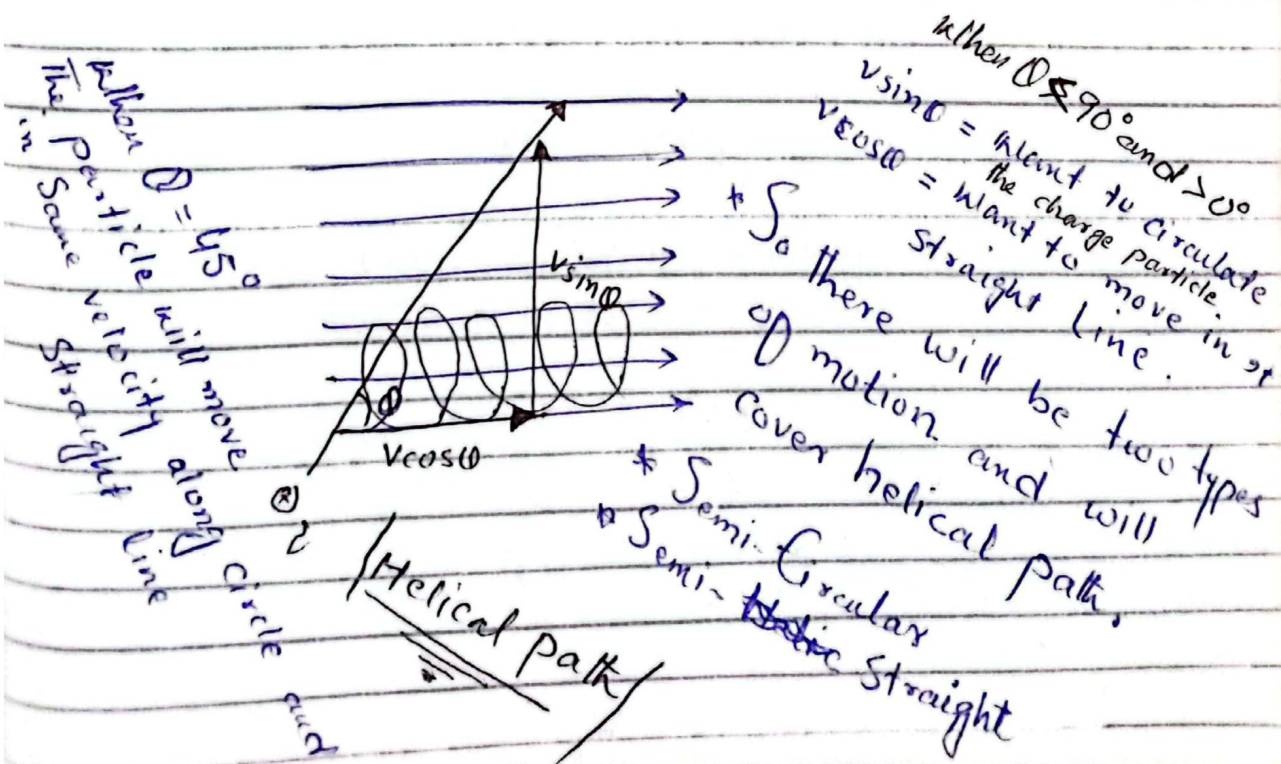
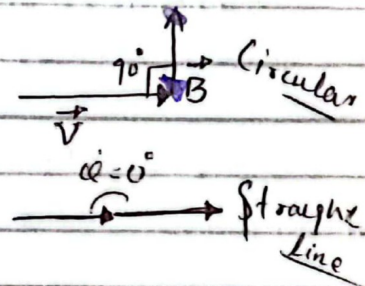
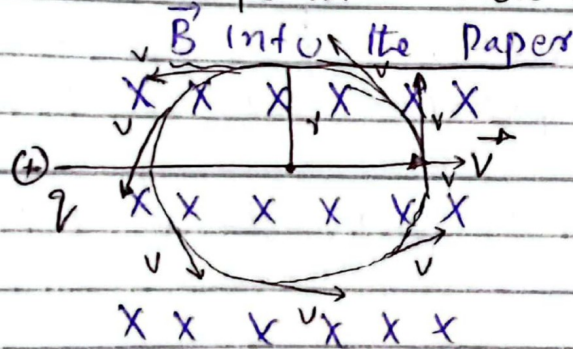
$$vB \sin \theta \hat{n} = \vec{v} \times \vec{B} \quad \text{--- (10)}$$

$$\vec{F}_m = q(\vec{v} \times \vec{B})$$

General formula for magnetic force...

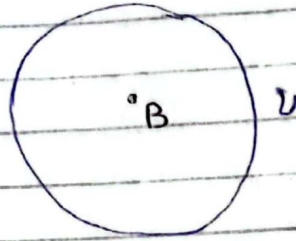
① When charge is displaced perpendicular in a magnetic field, the charge will circulate.

② When charge is displaced parallel → charge will move in Straight Line.



" \times $M_c Q$ "

* The magnetic field (B) is behaving like the axis of rotation for the particle...



* i) $\theta > 45^\circ$, particle will move faster in circle, slow in straight line

* ii) $\theta < 45^\circ$ particle will move faster in straight line.

Centripetal force is provided by magnetic force.

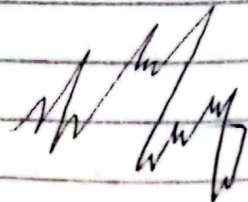
$$F_c = \frac{mv^2}{r} \quad \text{--- (1)}$$

$$F_m = qvB \quad \text{--- (2)}$$

Comparing (1) and (2)

$$\frac{mv^2}{r} = qvB$$

$$r = \frac{mv}{qB} \quad \text{--- (3)}$$



$$mv = qBr$$

$$v = \frac{qBr}{m} \quad (13)$$

$$v = r\omega$$

$$r\omega = \frac{qBr}{m}$$

$$\omega = \frac{qB}{m} \quad (14)$$

$$\omega = \frac{2\pi}{T}$$

$$\omega = 2\pi \left(\frac{1}{T} \right)$$

$$\omega = 2\pi f \quad (15) \quad (\because \frac{1}{T} = f)$$

put eq (15) in (14)

$$2\pi f = \frac{qB}{m}$$

$$f = \frac{qB}{2\pi m}$$

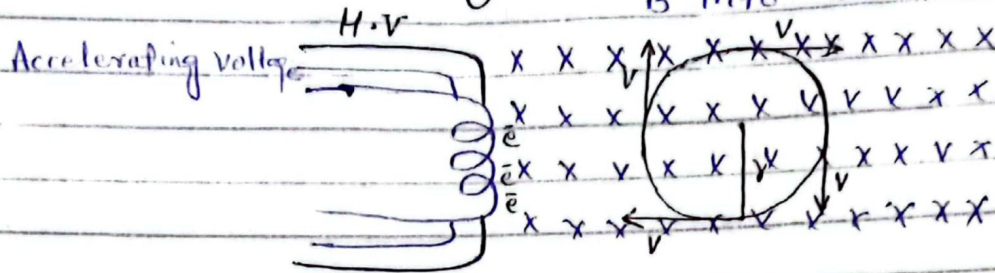
→ Cyclotron frequency.

Cyclotron: A machine by which we accelerate ~~the~~ charged particles.

Betatron: A machine by which we accelerate ~~the~~ charge particle.

Dated:- 27/10/2017

$\left(\frac{e}{m}\right)$ Ratio of an Electron:-
 \vec{B} Into the paper



Electron gun

Thermal Emission: Emission due to heat.

photoelectric Emission: Emission of e^- due to light

* For +ive charge:

$$F = q(\vec{v} \times \vec{B})$$

* For -ive charge,

$$(\vec{B} \times \vec{v})$$

$$\vec{F}_m = q(\vec{v} \times \vec{B})$$

$$q = -e$$

$$\vec{F}_m = -e(\vec{v} \times \vec{B})$$

$$\vec{F}_m = e(\vec{B} \times \vec{v}) \quad \text{--- (1)}$$

$$\therefore \vec{A} \times \vec{B} \neq \vec{B} \times \vec{A}$$

$$\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$

So,

$$\vec{v} \times \vec{B} \neq \vec{B} \times \vec{v}$$

$$\text{But } \vec{v} \times \vec{B} = -\vec{B} \times \vec{v}$$

$$-\vec{v} \times \vec{B} = \vec{B} \times \vec{v} \quad \text{--- (ii)}$$

$$\vec{F}_m = e(\vec{B} \times \vec{v})$$

$$* F_m = eBv \sin \theta$$

$$F_m = eVB \sin(90^\circ) \quad (\because B \perp V)$$

$$F_m = eVB \quad \text{--- (iii)}$$

The (F_m) Supply Centripetal force which is:

$$F_c = \frac{mv^2}{r} \quad \text{--- (iv)}$$

Compare (iii) and (iv):

$$eVB = \frac{mv^2}{r}$$

$$eB = \frac{mv}{r}$$

$$\left(\frac{e}{m}\right) = \frac{v}{Br}$$

$$\left(\frac{e}{m}\right) B = \frac{mv}{r} = \frac{eBr}{m}$$

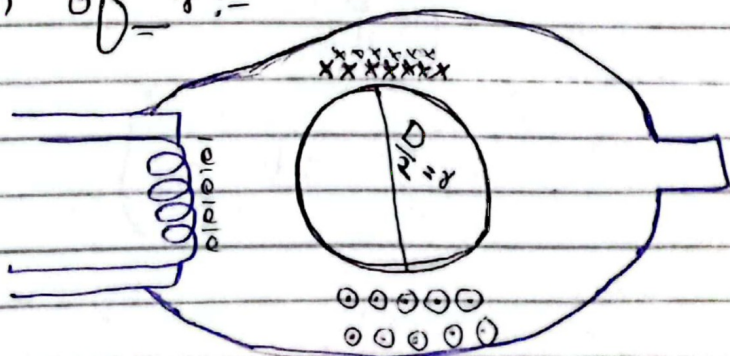
$B = \text{Constant}$.

problem is v and r ...

So we calculate st..

① Determination of r :-

performed in Dark room



$$\gamma = \frac{D}{2}$$

2. Determination of velocity (v):

When we apply A.V \rightarrow The e^- are accelerating and produce K.E.

$$\text{K.E} = \frac{1}{2}mv^2 \quad (4)$$

$$\text{K.E} = eV \quad (5)$$

Compare (4) and (5):

$$\frac{1}{2}mv^2 = eV$$

$$\frac{mv^2}{2} = eV$$

$$v = \sqrt{\frac{2eV}{m}} \quad (6)$$

put eq (6) in eq (5):

$$F = eVB$$

$$\left(\frac{e}{m}\right) = \frac{1}{B^2 r^2} \sqrt{\frac{2eV}{m}}$$

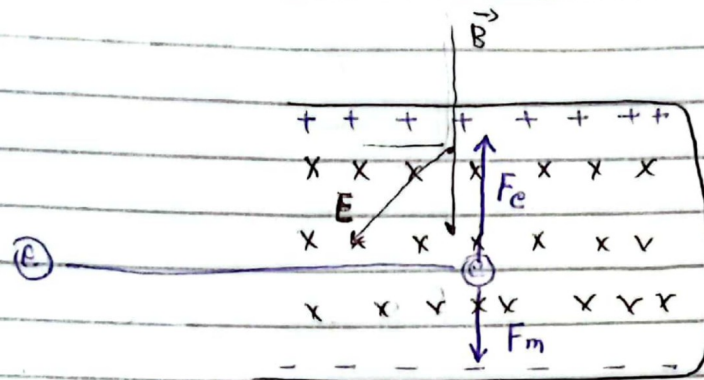
Taking Square On b.s.

$$\left(\frac{e}{m}\right)^2 = \frac{1}{B^2 r^2} \frac{2eV}{m}$$

$$\left(\frac{e}{m}\right)^2 = \left(\frac{e}{m}\right) \frac{2V}{B^2 r^2}$$

$$\left(\frac{e}{m}\right) = \frac{2V}{B^2 r^2} \quad (7)$$

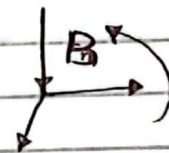
Method # 2; For Determination of $\left(\frac{e}{m}\right)$ of \bar{e} s.
particle Velocity Selector Method:



$$F_m = q (\vec{B} \times \vec{V}) \text{ For } \bar{e}s.$$

As,

$$F_m = eVB \text{ --- (8)}$$



$$F_e = eE \text{ --- (9)}$$

Compare (8) and (9):

$$eVB = eE$$

$$VB = E$$

$$V = \frac{E}{B} \text{ --- (10)}$$

put (10) in (3):

$$\left(\frac{e}{m}\right) = \frac{E}{B^2 d}$$

i.e. $V = \frac{E}{B}$

maximum $\left(\frac{E}{B}\right)$ ratio...

Some \bar{e} s are selected to move in straight line... Therefore velocity selector method.

$$V = \frac{E}{B}$$

pp

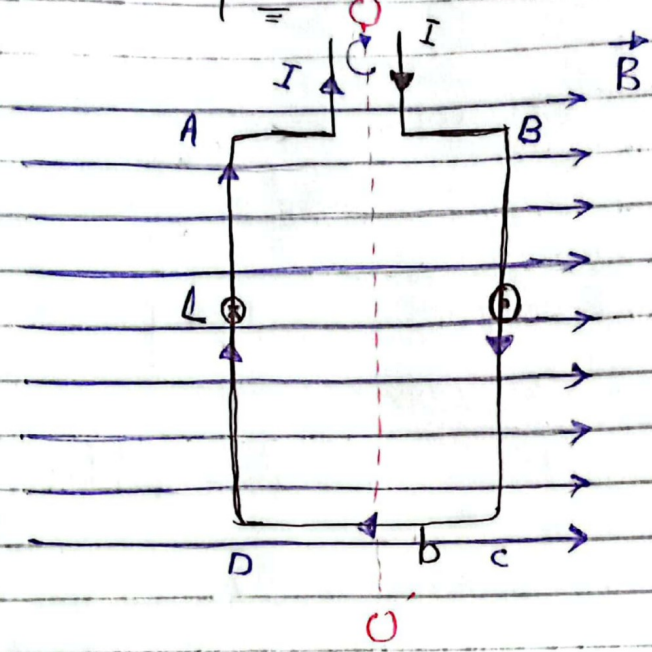
m

7

28 Oct, 2017

Torque on a Current carrying coil placed in a Uniform magnetic field:-

*A couple is Acting on the Coil. It is resultant of Couple Forces.



Force on Side AB:

$$F_m = ILB \sin(0^\circ) \quad (\because \theta = 0)$$

$$F_m = ILB(0)$$

$$F_m = 0$$

Force on Side CD:-

$$F_m = ILB \sin(180^\circ)$$

$$F_m = 0 \quad (\because \sin(180^\circ) = 0)$$

Magnetic force on BC:-

$$F_m = ILB \sin \theta$$

$$F_m = ILB \sin(90^\circ)$$

$$F_m = ILB \text{ ————— (i)}$$

Magnetic force on DA:-

$$F_m = ILB \sin(90^\circ)$$

$$F_m = ILB \text{ ————— (ii)}$$

*

Couple = product of the magnitude of either force \times perpendicular distance.

$$\tau = Fmb \quad \text{--- (3)}$$

put eq (1) or (2) in (3):

$$\tau = ILbB$$

$$\tau = NILbB$$

($\because N = 1$ if there are N number of turns in coil)

$$\because l b = A$$

$$\tau = BINA \quad \text{--- (4)}$$

$BINA$ is the torque Acting on the coil.

Generalizing:-

$$\tau = BINA \cos \theta$$

θ = Angle b/w B and plane of the coil.



$$\cos(0^\circ) = 1$$

$$\tau = BINA \sin \theta$$



$$\cos(90^\circ) = 0$$

$$\tau = BINA \sin \alpha$$

$$\alpha = 90^\circ$$

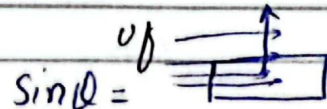
$$\theta = 0^\circ$$

α = Angle b/w

$$\alpha = 0^\circ$$

B and plane

$$\theta = 90^\circ$$



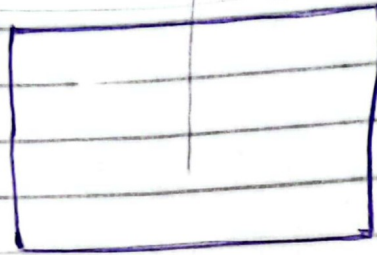
$$\sin \theta =$$

$$\sin(0^\circ) = 0 \quad \theta = 90^\circ = \sin(90^\circ) = 1$$

θ = Angle b/w B and plane of coil
 α = Angle b/w B and normal to plane of coil
 $\theta = 0^\circ \Rightarrow \alpha = 90^\circ$
 $\theta = 90^\circ \Rightarrow \alpha = 0^\circ$
 $\sin 0^\circ = 0$
 $\sin 90^\circ = 1$

✓ ip
* When flux is zero = Torque will be maximum

* When flux is maximum - torque will be minimum.



$$\alpha = 0^\circ$$

$$\alpha = 90^\circ$$



Nm #3: Data:

$$B = 1T$$

$$F_m = 2 \times 10^{-12} N$$

$$q = 1.6 \times 10^{-19} C$$

$$m = 1.67 \times 10^{-27} kg$$

Required:

$$v = ?$$

$$\vec{F}_m = q(\vec{v} \times \vec{B})$$

$$F_m = qvB \sin \theta$$

$$F_m = qvB \quad \theta = 90^\circ$$

$$B = \frac{F_m}{qv}$$

④ Data:

$$K.E = 8 \text{ MeV}$$

$$K.E = 8 \times 10^6 \text{ eV}$$

$$1 \text{ eV} = 1.6 \times 10^{-19} \text{ J}$$

$$K.E = 12.8 \times 10^{-13} \text{ J}$$

$$q = 1.6 \times 10^{-19} \text{ C}$$

$$m = 1.67 \times 10^{-27} \text{ kg}$$

Req: (a) $F_m = ?$

(b) $\gamma = ?$

$$(a) F_m = qvB \text{ --- (1)}$$

$$K.E = \frac{1}{2} mv^2$$

$$v = \sqrt{\frac{2(K.E)}{m}} \text{ --- (2)}$$

$$F_c = \frac{mv^2}{r}$$

$$F_m = qvB$$

$$\frac{mv^2}{r} = qvB$$

$$\frac{mv}{r} = qB$$

$$\boxed{\gamma = \frac{mv}{qB}}$$

⑤ Data:

$$(F_m)_1 = I_1 L B$$

$$\frac{2}{10 \times 10^{-3}} = \frac{10 \times 10^{-3}}{10 \times 10^{-3}} L B$$

$$L B = 200 ?$$

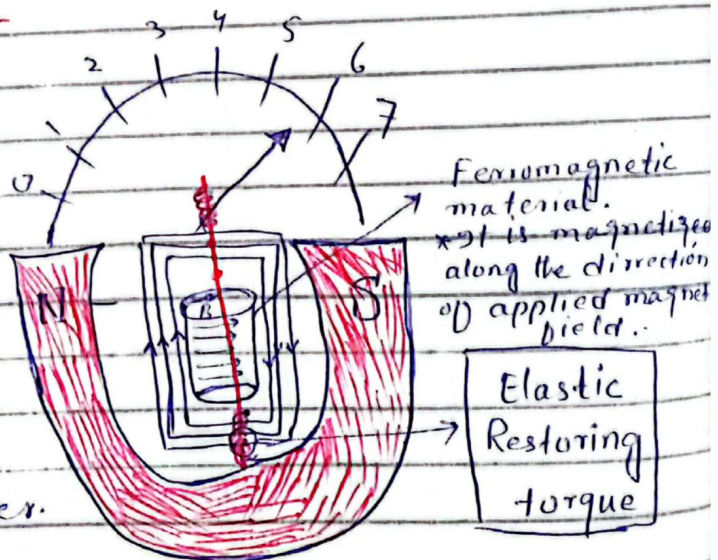
$$(F_m)_2 = I_2 L B$$
$$= 30 \times 10^{-3} \times 200$$
$$= 6 \times 10^{-3} \times 10^3$$

$$(F_m)_2 = 6 N$$

30 Oct 2017

① Galvanometer:-

A device by which we can determine (detect) the current in a circuit is called Galvanometer.



* Galvanometer is current detector not current measurer.

② Principles:-

A current carrying coil placed in a

uniform magnetic field is acted upon by a torque.

① Deflecting torque:

$$T_D = BINA \cos \theta$$

$$\therefore \theta = 0^\circ$$

$$T_D = BINA \cos 0$$

$$\boxed{T_D = BINA \text{ --- (i)}}$$

② Elastic Restoring torque:-

$$T_R \propto \theta \quad \begin{array}{l} \text{(Angle of deflection)} \\ \text{(Always taken in Rad)} \end{array}$$

$$T_R = C\theta \text{ --- (ii)}$$

where,

$$C = \frac{T_R}{\theta} \text{ --- (iii)}$$

"Elastic Restoring torque per unit deflection"

"C" Depends upon the materials of the spring.

if $\theta = \text{Less}$ (spring is Hard)

then $T_R = \text{More}$ (For More torque will be Stored).

where, C is called Torsion Constant.

Compare (i) and (ii):

$$BINA = CQ$$

Factor $I = \left(\frac{C}{BNA}\right) Q \quad \text{--- (k)}$

$$I = \text{constant (Q)}$$

$$I \propto Q$$

Sensitivity Galvanometer:

Galvanometer

which shows deflection for small current.

* Sensitivity of galvanometer

depends on the Factor $\left(\frac{C}{BNA}\right)$.

* "C" should be taken normal to maintain sensitivity.



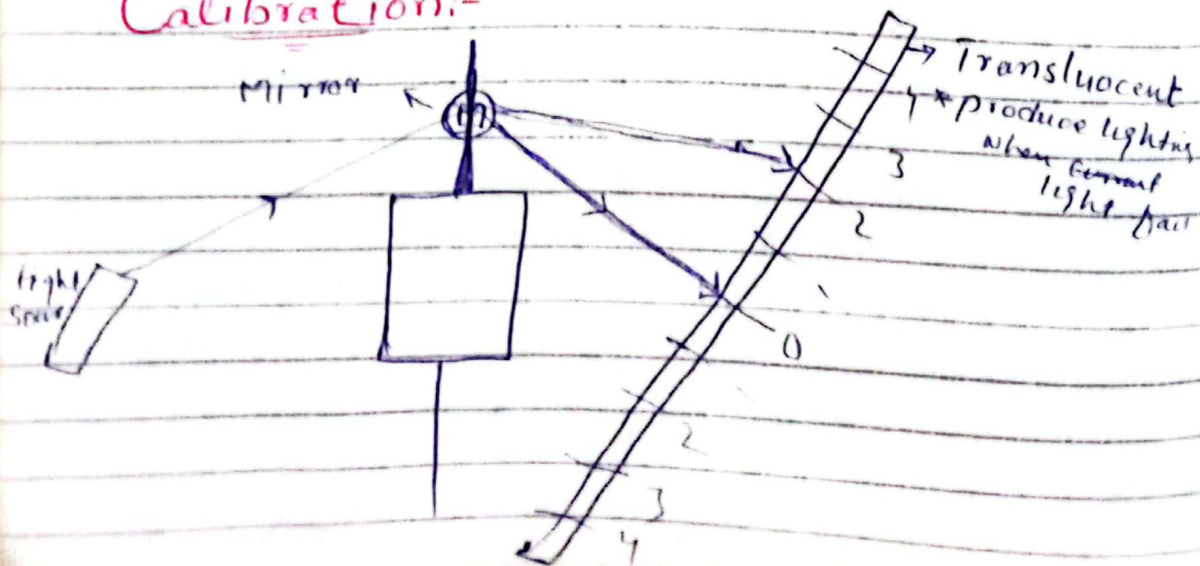
$$10 = 10(1)$$

$$10 = 5(2)$$

$$10 = 1(10)$$

$$I = \frac{C}{BNA} Q$$

Calibration:-



if $\theta = 20^\circ$
 $20^\circ = 2 \text{ div}$
 $2 \text{ div} = 20^\circ$
 $1 \text{ div} = 10^\circ$

- ① Calc convert $\theta = \text{Radian}$.
- ② calculate I for this angle

Suppose $I = 2A$

$$\begin{aligned} 2 \text{ div} &= 2A \\ 1 \text{ div} &= 1A \end{aligned}$$

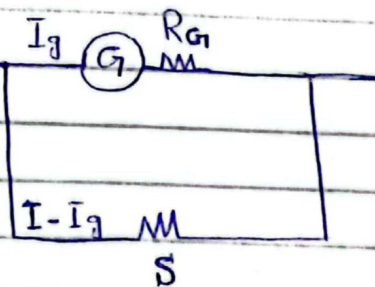
31 OCT, 2017

Conversion of Galvanometer into Ammeter and voltmeter.

① Ammetre :-

Defⁿ " A device by which we can measure current is called Ammetre.

- ① Current I Passes through G and S .
- ② As G and S are in parallel, so the I will divide into two parts.
 I_g and $I - I_g$.



* The potential difference across G and

S is the same.

* The current can be measured by an Ammeter, the desired value of current I_g passes through galvanometre can be achieved by changing Shunt.

Now, Potential of shunt = potential of galv-

$$V_s = V_g$$
$$(I - I_g) S = I_g R_g$$

$$R_s = \frac{I_g R_g}{I - I_g}$$

S = Shunt Resistance...

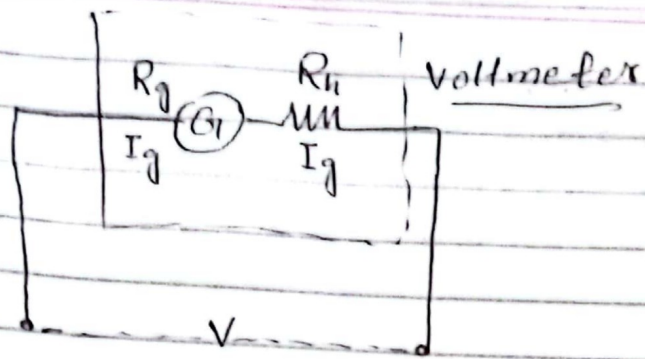
An Ideal Ammeter has Zero Resistance

Conversion of Galvanometre into Voltmetre :-

Def " A device which is used to measure potential difference b/w

two points in a circuit is called Voltmetre.

* Galvanometre can be converted into Voltmetre by connecting a high resistance (R_h) in ~~parallel~~ series with galvanometre.



$$V = V_g + V_h$$

$$V = I_g R_g + I_g R_h$$

$$V = I_g (R_g + R_h)$$

$$R_h = \frac{V}{I_g} - R_g$$

This is the equation for the resistance to be connected with galvanometer in series...

* The value of R_h is High. So the equivalent resistance of voltmeter is High.

Due to its high resistance the voltmeter do not draw any current from the circuit. Only it measure the potential difference b/w two points.

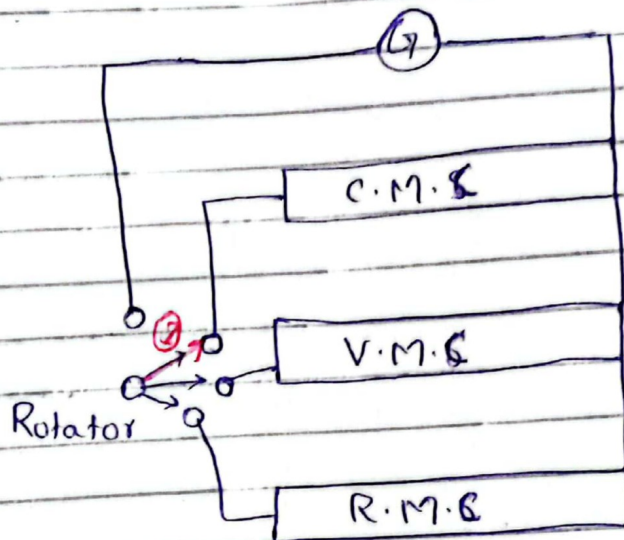
01/Nov/2017

Avo metre (Multi-metre):-

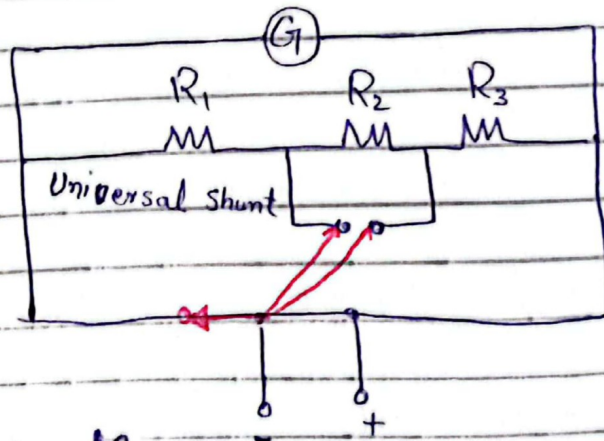
I
V
R,

A Device by which we measure Current, Voltage and

Resistance is called Avo-metre or Multi-metre.

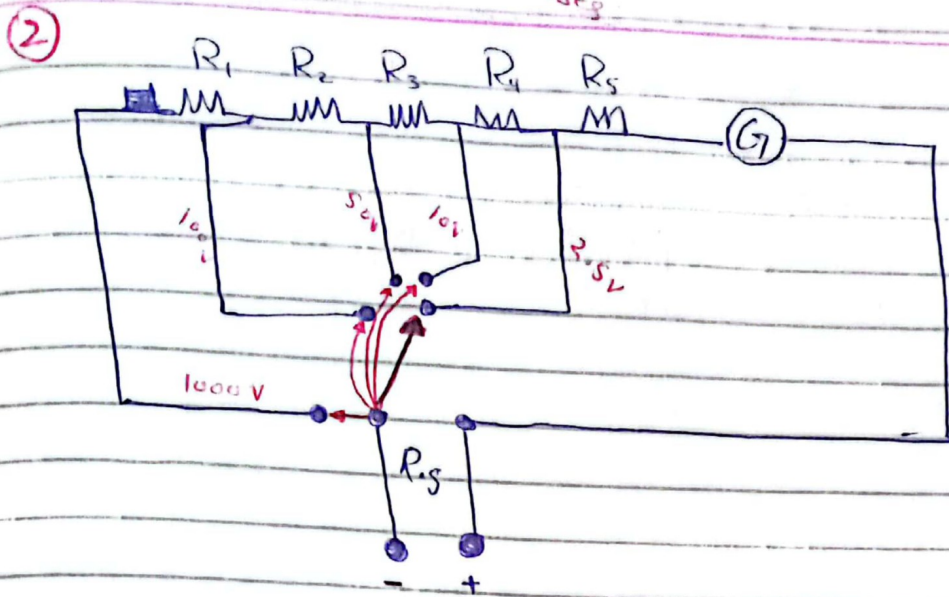


① As a Ammetre



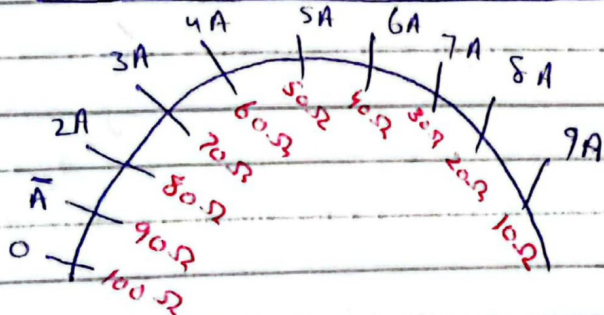
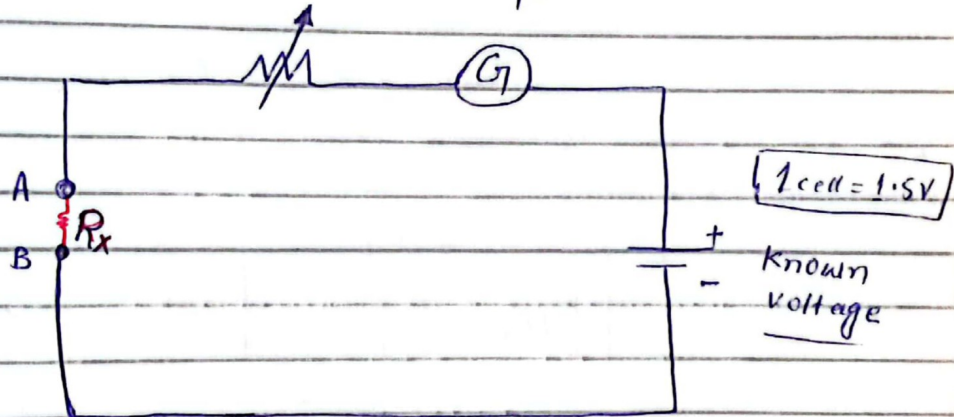
Multi-range Ammetre

Range will increase



(3) As A Resistor (Ohmmeter)

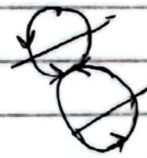
Use to change the resistance.



$$V = IR_x$$

$$R_x = \frac{V}{I}$$

V = known
I = from scale

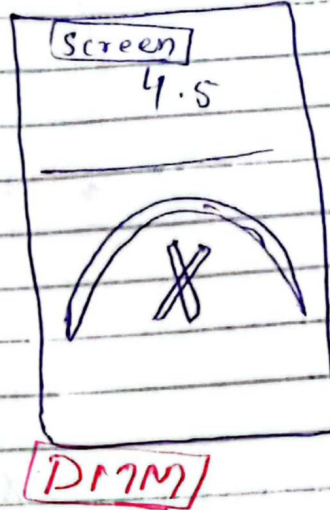


Digital Multi-metre (DMM) :-

* No Scale.

* Screen is present which show the result.

* DMM is better than analogue multi-metre.



The End

عبدالله
ابراهيم ادوراه
31-01-2020